

**Lecture 3**  
**Convex Functions**

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# Outline

- Convex Functions
- Examples
- Verifying Convexity of a Function
- Operations on Functions Preserving Convexity

## Convex Functions

Informally:  $f$  is convex when for every segment  $[x_1, x_2]$ , as  $x_\alpha = \alpha x_1 + (1 - \alpha)x_2$  varies over the line segment  $[x_1, x_2]$ , the points  $(x_\alpha, f(x_\alpha))$  lie below the segment connecting  $(x_1, f(x_1))$  and  $(x_2, f(x_2))$

Let  $f$  be a function from  $\mathbb{R}^n$  to  $\mathbb{R}$ ,  $f : \mathbb{R}^n \rightarrow \mathbb{R}$

The domain of  $f$  is a set in  $\mathbb{R}^n$  defined by

$$\text{dom}(f) = \{x \in \mathbb{R}^n \mid f(x) \text{ is well defined (finite)}\}$$

**Def.** A function  $f$  is *convex* if

- (1) Its domain  $\text{dom}(f)$  is a convex set in  $\mathbb{R}^n$  and
- (2) For all  $x_1, x_2 \in \text{dom}(f)$  and  $\alpha \in (0, 1)$

$$f(\alpha x_1 + (1 - \alpha)x_2) \leq \alpha f(x_1) + (1 - \alpha)f(x_2)$$

## More on Convex Function

**Def.** A function  $f$  is *strictly convex* when  $\text{dom}(f)$  is convex and

$$f(\alpha x_1 + (1 - \alpha)x_2) < \alpha f(x_1) + (1 - \alpha)f(x_2)$$

for all  $x_1, x_2 \in \text{dom}(f)$  and  $\alpha \in (0, 1)$

**Def.** A function  $f$  is *concave* when  $-f$  is convex, i.e.,

(1) Its domain  $\text{dom}(f)$  is a convex set in  $\mathbb{R}^n$  and

(2) For all  $x_1, x_2 \in \text{dom}(f)$  and  $\alpha \in (0, 1)$

$$f(\alpha x_1 + (1 - \alpha)x_2) \geq \alpha f(x_1) + (1 - \alpha)f(x_2)$$

**Def.** A function  $f$  is *strictly concave* when  $-f$  is strictly convex

## Examples on $\mathbb{R}$

Convex:

- Affine:  $ax + b$  over  $\mathbb{R}$  for any  $a, b \in \mathbb{R}$
- Exponential:  $e^{ax}$  over  $\mathbb{R}$  for any  $a \in \mathbb{R}$
- Power:  $x^p$  over  $(0, +\infty)$  for  $p \geq 1$  or  $p \leq 0$
- Powers of absolute value:  $|x|^p$  over  $\mathbb{R}$  for  $p \geq 1$
- Negative entropy:  $x \ln x$  over  $(0, +\infty)$

Concave:

- Affine:  $ax + b$  over  $\mathbb{R}$  for any  $a, b \in \mathbb{R}$
- Powers:  $x^p$  over  $(0, +\infty)$  for  $0 \leq p \leq 1$
- Logarithm:  $\ln x$  over  $(0, +\infty)$

## Examples: Affine Functions and Norms

- Affine functions are both convex and concave
- Norms are convex

### Examples on $\mathbb{R}^n$

- Affine function  $f(x) = a'x + b$  with  $a \in \mathbb{R}^n$  and  $b \in \mathbb{R}$
- Euclidean,  $l_1$ , and  $l_\infty$  norms
- General  $l_p$  norms

$$\|x\|_p = \left( \sum_{i=1}^n |x_i|^p \right)^{1/p} \quad \text{for } p \geq 1$$

## Examples on $\mathbb{R}^{m \times n}$

The space  $\mathbb{R}^{m \times n}$  is the space of  $m \times n$  matrices

- Affine function

$$f(X) = \text{tr}(A^T X) + b = \sum_{i=1}^m \sum_{j=1}^n a_{ij} x_{ij} + b$$

- Spectral (maximum singular value) norm

$$f(X) = \|X\|_2 = \sigma_{\max}(X) = \sqrt{\lambda_{\max}(X^T X)}$$

where  $\lambda_{\max}(A)$  denotes the maximum eigenvalue of a matrix  $A$

## Verifying Convexity of a Function

We can verify that a given function  $f$  is convex by

- Using the definition
- Applying some special criteria
  - Second-order conditions
  - First-order conditions
  - Reduction to a scalar function
- Showing that  $f$  is obtained through operations preserving convexity



## Second-Order Conditions

Let  $f$  be **twice differentiable** and let  $\text{dom}(f) = \mathbb{R}^n$  [in general, it is required that  $\text{dom}(f)$  is open]

The Hessian  $\nabla^2 f(x)$  is a symmetric  $n \times n$  matrix whose entries are the second-order partial derivatives of  $f$  at  $x$ :

$$\left[ \nabla^2 f(x) \right]_{ij} = \frac{\partial^2 f(x)}{\partial x_i \partial x_j} \quad \text{for } i, j = 1, \dots, n$$

**2nd-order conditions:** For a twice differentiable  $f$  with convex domain

- $f$  is convex if and only if

$$\nabla^2 f(x) \succeq 0 \quad \text{for all } x \in \text{dom}(f)$$

- $f$  is strictly convex if

$$\nabla^2 f(x) \succ 0 \quad \text{for all } x \in \text{dom}(f)$$

## Examples

**Quadratic function:**  $f(x) = (1/2)x'Px + q'x + r$  with a symmetric  $n \times n$  matrix  $P$

$$\nabla f(x) = Px + q, \quad \nabla^2 f(x) = P$$

Convex for  $P \succeq 0$

**Least-squares objective:**  $f(x) = \|Ax - b\|^2$  with an  $m \times n$  matrix  $A$

$$\nabla f(x) = 2A^T(Ax - b), \quad \nabla^2 f(x) = 2A^T A$$

Convex for any  $A$

**Quadratic-over-linear:**  $f(x, y) = x^2/y$

$$\nabla^2 f(x, y) = \frac{2}{y^3} \begin{bmatrix} y \\ -x \end{bmatrix} \begin{bmatrix} y \\ -x \end{bmatrix}^T \succeq 0$$

Convex for  $y > 0$

## Verifying Convexity of a Function

We can verify that a given function  $f$  is convex by

- Using the definition
- Applying some special criteria
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  - First-order conditions
  - Reduction to a scalar function
- Showing that  $f$  is obtained through operations preserving convexity

## First-Order Condition

$f$  is *differentiable* if  $\text{dom}(f)$  is open and the gradient

$$\nabla f(x) = \left( \frac{\partial f(x)}{\partial x_1}, \frac{\partial f(x)}{\partial x_2}, \dots, \frac{\partial f(x)}{\partial x_n} \right)$$

exists at each  $x \in \text{dom} f$

**1st-order condition:** differentiable  $f$  is convex if and only if *its domain is convex* and

$$f(x) + \nabla f(x)^T(z - x) \leq f(z) \quad \text{for all } x, z \in \text{dom}(f)$$

*A first order approximation is a global underestimate of  $f$*

Very important property used in algorithm designs and performance analysis

## Restriction of a convex function to a line

$f$  is convex if and only if  $\text{dom} f$  is convex and the function  $g : \mathbb{R} \rightarrow \mathbb{R}$ ,

$$g(t) = f(x + tv), \quad \text{dom} g = \{t \mid x + tv \in \text{dom}(f)\}$$

is convex (in  $t$ ) for any  $x \in \text{dom} f$ ,  $v \in \mathbb{R}^n$

*Checking convexity of multivariable functions can be done by checking convexity of functions of one variable*

Example  $f : \mathcal{S}^n \rightarrow \mathbb{R}$  with  $f(X) = -\ln \det X$ ,  $\text{dom} f = \mathcal{S}_{++}^n$

$$\begin{aligned} g(t) &= -\ln \det(X + tV) = -\ln \det X - \ln \det(I + tX^{-1/2}VX^{-1/2}) \\ &= -\ln \det X - \sum_{i=1}^n \ln(1 + t\lambda_i) \end{aligned}$$

where  $\lambda_i$  are the eigenvalues of  $X^{-1/2}VX^{-1/2}$   
 $g$  is concave in  $t$  (for any choice of  $V$  and any  $X \succ 0$ ); hence  $f$  is concave

## Operations Preserving Convexity

- Positive Scaling
- Sum
- Composition with affine function
- Pointwise maximum and supremum
- Composition
- Minimization

## Scaling, Sum, & Composition with Affine Function

*Positive multiple* For a convex  $f$  and  $\lambda > 0$ , the function  $\lambda f$  is convex

*Sum:* For convex  $f_1$  and  $f_2$ , the sum  $f_1 + f_2$  is convex  
(extends to infinite sums, integrals)

*Composition with affine function:* For a convex  $f$  and affine  $g$  [i.e.,  $g(x) = Ax + b$ ], the composition  $f \circ g$  is convex, where

$$(f \circ g)(x) = f(Ax + b)$$

### Examples

- Log-barrier for linear inequalities

$$f(x) = - \sum_{i=1}^m \ln(b_i - a_i^T x), \quad \text{dom } f = \{x \mid a_i^T x < b_i, i = 1, \dots, m\}$$

- (Any) Norm of affine function:  $f(x) = \|Ax + b\|$

## Pointwise maximum

For convex functions  $f_1, \dots, f_m$ , the *pointwise-max function*

$$F(x) = \max \{f_1(x), \dots, f_m(x)\}$$

is convex (What is domain of  $F$ ?)

Examples

- Piecewise-linear function:  $f(x) = \max_{i=1, \dots, m} (a_i^T x + b_i)$  is convex
- Sum of  $r$  largest components of a vector  $x \in \mathbb{R}^n$ :

$$f(x) = x_{[1]} + x_{[2]} + \dots + x_{[r]}$$

is convex ( $x_{[i]}$  is  $i$ -th largest component of  $x$ )

$$f(x) = \max_{(i_1, \dots, i_r) \in I_r} \{x_{i_1} + x_{i_2} + \dots + x_{i_r}\}$$

$$I_r = \{(i_1, \dots, i_r) \mid i_1 < \dots < i_r, i_j \in \{1, \dots, m\}, j = 1, \dots, r\}$$



## Pointwise Supremum

Let  $\mathcal{A} \subseteq \mathbb{R}^p$  and  $f : \mathbb{R}^n \times \mathbb{R}^p \rightarrow \mathbb{R}$ . Let  $f(x, z)$  be convex in  $x$  for each  $z \in \mathcal{A}$ . Then, *the supremum function over the set  $\mathcal{A}$  is convex*:

$$g(x) = \sup_{z \in \mathcal{A}} f(x, z)$$

### Examples

- *Set support function is convex* for a set  $C \subset \mathbb{R}^n$ ,

$$S_C : \mathbb{R}^n \rightarrow \mathbb{R}, \quad S_C(x) = \sup_{z \in C} z^T x$$

- *Set farthest-distance function is convex* for a set  $C \subset \mathbb{R}^n$ ,

$$f : \mathbb{R}^n \rightarrow \mathbb{R}, \quad f(x) = \sup_{z \in C} \|x - z\|$$

- *Maximum eigenvalue function of a symmetric matrix is convex*

$$\lambda_{\max} : \mathcal{S}^n \rightarrow \mathbb{R}, \quad \lambda_{\max}(X) = \sup_{\|z\|=1} z^T X z$$

## Composition with Scalar Functions

Composition of  $g : \mathbb{R}^n \rightarrow \mathbb{R}$  and  $h : \mathbb{R} \rightarrow \mathbb{R}$  with  $\text{dom}(g) = \mathbb{R}^n$  and  $\text{dom}(h) = \mathbb{R}$ :

$$f(x) = h(g(x))$$

$f$  is convex if

(1)  $g$  is convex,  $h$  is nondecreasing and convex

(2)  $g$  is concave,  $h$  is nonincreasing and convex

Examples

- $e^{g(x)}$  is convex if  $g$  is convex
- $\frac{1}{g(x)}$  is convex if  $g$  is concave and positive

## Composition with Vector Functions

Composition of  $g : \mathbb{R}^n \rightarrow \mathbb{R}^p$  and  $h : \mathbb{R}^p \rightarrow \mathbb{R}$  with  $\text{dom}(g) = \mathbb{R}^n$  and  $\text{dom}(h) = \mathbb{R}^p$ :

$$f(x) = h(g(x)) = h(g_1(x), g_2(x), \dots, g_p(x))$$

$f$  is convex if

(1) each  $g_i$  is convex,  $h$  is convex and nondecreasing in each argument

(2) each  $g_i$  is concave,  $h$  is convex and nonincreasing in each argument

Example

- $\sum_{i=1}^m e^{g_i(x)}$  is convex if  $g_i$  are convex

## Extended-Value Functions

A function  $f$  is an *extended-value function* if  $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{-\infty, +\infty\}$

Example: consider  $f(x) = \inf_{y \geq 0} xy$  for  $x \in \mathbb{R}$

**Def.** The *epigraph* of a function  $f$  over  $\mathbb{R}^n$  is the following set in  $\mathbb{R}^{n+1}$ :

$$\text{epi} f = \{(x, w) \in \mathbb{R}^{n+1} \mid x \in \mathbb{R}^n, f(x) \leq w\}$$

**General Convex Function Def.** A function  $f$  is *convex* if its epigraph  $\text{epi} f$  is a convex set in  $\mathbb{R}^{n+1}$

This definition is equivalent to the one we have used so far (when reduced to the function class we have considered thus far). How?

For an  $f$  with domain  $\text{dom} f$ , we associate an extended-value function  $\tilde{f}$  defined by

$$\tilde{f}(x) = \begin{cases} f(x) & \text{if } x \in \text{dom} f \\ +\infty & \text{otherwise} \end{cases}$$

$\text{dom} f$  is the projection of  $\text{epi} f$  on  $\mathbb{R}^n$ ; convexity of  $f$  by letting  $w = f(x)$

## Minimization

Let  $C \subseteq \mathbb{R}^n \times \mathbb{R}^p$  be a *nonempty convex* set

Let  $f : \mathbb{R}^n \times \mathbb{R}^p \rightarrow \mathbb{R}$  be a *convex* function [in  $(x, z) \in \mathbb{R}^n \times \mathbb{R}^p$ ]. Then

$$g(x) = \inf_{z \in C} f(x, z) \quad \text{is convex}$$

Example

- Distance to a set: for a nonempty convex  $C \subset \mathbb{R}^n$ ,

$$\text{dist}(x, C) = \inf_{z \in C} \|x - z\| \quad \text{is convex}$$

Proof: Let  $x_1, x_2 \in \mathbb{R}^n$  and  $\alpha \in (0, 1)$  be arbitrary. Let  $\epsilon > 0$  be arbitrarily small. Then, there exist  $z_1, z_2 \in C$  such that  $f(x_1, z_1) \leq g(x_1) + \epsilon$  and  $f(x_2, z_2) \leq g(x_2) + \epsilon$ . Consider  $f(\alpha x_1 + (1 - \alpha)x_2, \alpha z_1 + (1 - \alpha)z_2)$  and use convexity of  $f$  and  $C$ .